

Australian Government Department of Agriculture, Water and the Environment

# Using advances in technology for biosecurity risk detection

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Biosecurity Operations Division

Department of Agriculture, Water and the Environment

#### **Emerging Technology Program**



#### **Our Investment in New 3D X-ray Technology**





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**3D View** 



# **Algorithm Development**

### **3D Algorithm Development**

Current Algorithm Development In partnership with NZMPI and Rapiscan we have developed algorithms to automatically detect biosecurity risks for: Meat Fruit Vegetables Seafood 3D xray Algorith m on 3D x-ray





### **Concealed Succulents**



The power of a 3D X-Ray

 Following the initial 3D X-Ray scan the parcel was inspected and found to have 83 succulents concealed within decorative cushions.





### **3D Algorithm Development**

#### Melbourne Jet Base Testing Facility 🖍

- An RTT 110 3D x-ray unit located at Melbourne Jet Base is being used to validate algorithms and build our image library.
- High risk commodities are scanned through the machine multiple times, in different positions, placed in bags and boxes with items of no concern.
- The more the commodity is scanned the stronger the algorithm becomes ensuring a higher rate of detection.





### **2D Algorithm Development**

As well as our successful work on 3D x-ray, we continue to trial our 2D x-ray automated detection algorithms at our dog facility in Brisbane. The department is partnering with both Rapiscan and Smiths to inform our future 2D hardware and software strategy.

#### Rapiscan 927 DX 2D x-ray unit

- Trial commenced early 2021 •
- Building meat image library to provide data to inform algorithm development
- Meat detection algorithm is soon to be deployed on to the Rapiscan 2D x-ray unit





Smiths 100 100 V-2IS 2D x-ray unit unit

- The trial for the Smith's unit is in early stages of data • gathering and validation
- Focus is on validating algorithms and building the ٠ image library



future

Passenger Baggage Pre-Screening Trial

### **Passenger Baggage Pre-Screening Trial**



- The onshore trial will screen hold baggage after arrival but prior to the passenger collecting their baggage
- As bags are unloaded onto the baggage handling system they will be scanned by the 3D x-ray unit
- 3D x-ray images will be sent to a control room where biosecurity officers will assess the contents for biosecurity risk material



### Passenger Baggage Pre-Screening Trial



## **3D X-Ray in Mail Centres**

#### **Our Investment in New 3D X-ray Technology**

#### **3D X-ray in Mail Centres**

 The purpose of the project is to build on the early benefits that have been realised through existing RTT installations at SGF & MGF mail centres

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- Three additional RTT 3D x-ray units will be installed at international mail centres
- The additional RTT units will further enhance and streamline the detection of biosecurity risks









### **Remote Screening**

#### Sydney Gateway Facility

- Our first remote screening room has been set up at the Sydney Gateway Facility.
- Biosecurity Officers will have the ability to screen incoming mail without physically having to be on the operational floor.
- Screening rate increased over traditional screening method









New and Emerging Technologies

### **Biosecurity Innovation Program**

The Biosecurity Innovation Program invests in new technologies and approaches to enhance Australia's biosecurity system.





### Low Energy X-ray for Seeds

Seed Automated Algorithm

- Current 2D or 3D x-rays are too high energy resulting in them not detecting small seeds.
- High energy x-ray is likely to penetrate through the item resulting in no image being produced.
- Low energy, high resolution x-ray technology is currently in stage three of the project.
- It is expected the prototype will be trialled at a mail gateway facility following the conclusion of phase 4.



#### Phase 1

Phase 2

Phase one successfully tested the prototype and proof of concept on a stand-alone unit.

Phase two of the project had Rapiscan prove the concept of auto-detection of seed packets and their contents using video cameras, low energy x-ray and computer algorithms on a moving conveyor system.

Phase 3

Validating the bespoke solution to prove high algorithm efficacy rates with increased throughput levels.

Phase 4

Phase will deploy a full prototype unit at Melbourne Jet Base to test conveyors and robot pickers in a final trial. Currently scheduled to conclude in late 2022.



#### **Hades-5Z Inspection Robot**



#### Purpose

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- Conduct vehicle (used and new) and used machinery inspections
- Reduce WHS risk for biosecurity officers
- Safer inspections for Biosecurity Officers

#### The Technology

- Remote-controlled device
- Fitted with both a thermal & high-definition camera
- Specialising in crawl space inspections

#### The trial will test the robot's ability to:

The Trial

- Maneuver across a range of surfaces
- Provide accurate images identifying biosecurity risk materials under a range of environmental conditions
- Undertake safer and more efficient inspections



### RingIR

#### About RingIR

#### Detecting fumigants using real-time vapour detection

Phase 1 of this project confirmed that the RingIR technology can detect all three fumigants of concern - methyl bromide, sulfuryl fluoride and phosphine.

Phase 2 has commenced and is split into two sub-projects.

- 1. To develop a portable prototype to detect all three fumigants that could be trialled in our operations by 30 June 2022.
- 2. To test whether RingIR technology can be expanded to identify hitchhiker pests associated with containers.



- Biosecurity officers can work in a safe environment.
- Reduction in delays caused by possible Photo Ionisation Detector false alarms.
- Reduction in unnecessary treatment of containers where no pests are present.



# **Biosecurity Detector Dogs**

### **Biosecurity Detector Dogs**



**Detector Dog Fleet** 

- The current detector dog fleet consists of:
  - 42 Operational Dogs
  - 47 Handlers
  - 2 Dogs in training
- Latest dog to complete training "Finlay" is trialling a "Passive" response across all deployment scenarios.

#### **Target Commodities**

Detector dogs are trained to detect seven commodity groups, which are estimated to contain 200+ individual commodities:

- Fresh fruit
- Fresh vegetables
- Fresh plant material (including cuttings)
- Viable seeds and bulbs
- Meat (excluding fish)
- Eggs
- Brown Marmorated Stink Bugs (BMSB)







### **Detector Dogs Innovation**

#### **Detector Dog Innovation – Canine Character Assessment**

- The department is partnering with the University of New England to identify the traits and behaviours inherent in our top performing detector dogs.
- This work will inform the development of future detector dog selection processes.
- Researchers fit each dog with a specialised harness equipped with a variety of sensors, including an accelerometer and ECG monitor.





### Velvet – the first dog to sniff out BMSB

Sniffing out BMSB through the cargo pathway

- In 2018 we began an innovative project with the University of New England to train our detector dog fleet to sniff out Brown Marmorated Stink Bug (BMSB).
- In November 2021 Velvet was the first detector dog to find a live BMSB.
- During a cargo inspection of over 800 vehicles and over 150 bulk break items Velvet sniffed out a single live BMSB on an off highway Caterpillar Truck.
- This live sample was confirmed as a BMSB and subsequently used to train and test the entire Brisbane detector dog fleet.



# Questions

